

# TCNN on Images

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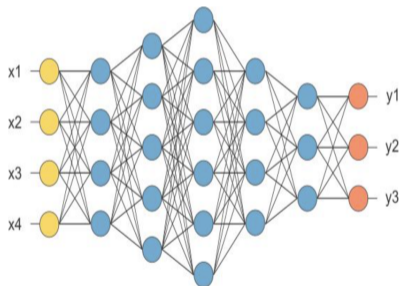
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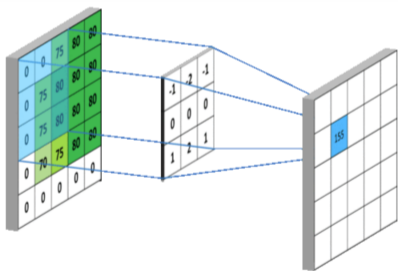
**5** Thanks

# Feed Forward Neural Network



- Each circle represents a **node**.
- All nodes in one column construct a layer, where the layer with yellow color is the **input layer**, the layer with orange color is the **output layer** and the other layers are **hidden layers**.
- The edge in this graph represents the correspondence between the nodes.

# Convolutional Kernel



- The left matrix is the data in the last layer.
- The middle matrix is the convolutional kernel.
- The right matrix is the data in the next layer.
- The data in the next layer is computed as the picture shows.

# A Formula for Klein Bottle

## A Formula for Klein Bottle

$$F_{\mathcal{K}}(\theta_1, \theta_2)(x, y) = \sin(\theta_2)(\cos(\theta_1)x + \sin(\theta_1)y) + \cos(\theta_2)Q(\cos(\theta_1)x + \sin(\theta_1)y),$$

where  $Q(t) = 2t^2 - 1$ . As given,  $F_{\mathcal{K}}$  is a function on the torus, which is parameterized by the two angles  $\theta_1$  and  $\theta_2$ . It actually defines a function on  $\mathcal{K}$  since it satisfies  $F_{\mathcal{K}}(\theta_1, \theta_2) = F_{\mathcal{K}}(\theta_1 + 2k\pi, \theta_2 + 2l\pi)$  and  $F_{\mathcal{K}}(\theta_1 + \pi, -\theta_2) = F_{\mathcal{K}}(\theta_1, \theta_2)$ .



## Two Basic Kernels

$$\begin{matrix} -1 & 0 & 1 \\ -1 & 0 & 1 \\ -1 & 0 & 1 \end{matrix}$$

**Table 1:** The First Kernel of Klein Bottles

$$\begin{matrix} 1 & -1 & 1 \\ 1 & -1 & 1 \\ 1 & -1 & 1 \end{matrix}$$

**Table 2:** The Second Kernel of Klein Bottles



# A Distance in Klein Bottle

The metric  $d_{\mathcal{K}}$  is defined by

## A Distance in Klein Bottle

$$d_{\mathcal{K}}(\kappa, \kappa') = \left( \int_{[-1,1]^2} (F_{\mathcal{K}}(\kappa)(x, y) - F_{\mathcal{K}}(\kappa')(x, y))^2 dx dy \right)^{\frac{1}{2}}$$

for  $\kappa, \kappa' \in \mathcal{K}$ .



# KF(CF) Layer

## KF (CF) Layer

Let  $M = S^1$  or  $\mathcal{K}$  and let  $\chi \subset M$  be a finite subset. Let  $V_i = \mathbb{Z}^2$  and  $V_{i+1} = X \times \mathbb{Z}^2$  be successive layers in a FFNN. Suppose  $V_{i+1}$  is a convolutional layer with threshold  $s \geq 0$ . Then  $V_{i+1}$  is called a **Circle Features (CF) layer** or a **Klein Features (KF) layer**, respectively, if the weights  $\lambda_{-, (\kappa, -, -)}$  are given for  $\kappa \in \chi$  by a convolution over  $V_i$  of the filter of size  $(2s+1) \times (2s+1)$  with values

$$\text{Filter}(\kappa)(n, m) = \int_{-1 + \frac{2m}{2s+1}}^{-1 + \frac{2(m+1)}{2s+1}} \int_{-1 + \frac{2n}{2s+1}}^{-1 + \frac{2(n+1)}{2s+1}} F_M(\kappa)(x, y) dx dy$$

for integers  $0 \leq n, m \leq 2s$ .





# The Construction of Kernels

- Let  $D$  be  $[-1, 1] \times [-1, 1]$ , consider the following function

$$f(x, y) = A + Bx + Cy + Dx^2 + Exy + Fy^2,$$

then it becomes a 6-dimensional vector space  $\mathcal{Q}$ .

- Let  $\int_D f = 0$  (mean centering) and  $\int_D f^2 = 1$  (normalization). It is a 4-dimensional space  $\mathcal{P} \subset \mathcal{Q}$ .
- Let  $f(x, y) = q(\lambda x + \mu y)$  with  $\lambda^2 + \mu^2 = 1$  (rotation invariance). It implies that the space is 2-dimensional  $\mathcal{P}_0 \subset \mathcal{P}$ .



## Kernels on a Klein Bottle

- Let  $\int_{-1}^1 q = 0$  and  $\int_{-1}^1 q^2 = 1$  with  $q(t) = c_0 + c_1 t + c_2 t^2$ , then  $q \in A$ , where  $A$  is homeomorphic to  $S^1$ . Let  $\mathbf{v} = (\lambda, \mu)$ , then  $f(x, y) = q(\mathbf{v} \cdot (x, y))$ . (Note that  $\mathbf{v} \in S^1$ .)
- Verify that  $\int_D f = 0$  and  $\int_D f^2 \neq 0$ . Define a map  $\theta : A \times S^1 \rightarrow \mathcal{P}_0$  by

$$\theta(q, \mathbf{v}) = \frac{q(\mathbf{v}, -)}{\|f\|_2}.$$

$\theta$  is not a homeomorphism. Define a map  $\rho : A \rightarrow A$  by

$$\rho(c_0 + c_1 t + c_2 t^2) = c_0 - c_1 t + c_2 t^2,$$

then  $\theta(q, \mathbf{v}) = \theta(\rho(q), -\mathbf{v})$ .

- Verify that  $\mathcal{P}_0$  is homeomorphic to a Klein bottle.



# Main Program

```
img_input = Input(shape=(32, 32, 3))
net = Conv2D(64, (3,3), activation='relu', padding = 'same')(img_input)
#net = CircleFeatures(64)(img_input)
net = KleinFeatures(64)(img_input)
net = MaxPooling2D(2,2)(net)
net = Conv2D(64, (3,3), activation='relu', padding = 'same')(net)
#net = CircleOneLayer(64)(net)
#net = KleinOneLayer(64)(net)
net = MaxPooling2D(2,2)(net)
net = Flatten()(net)
net = Dense(512, activation='relu')(net)
net = Dense(10)(net)
output = net

model1 = models.Model(img_input, output)
model1.summary()

model1.compile(optimizer=tf.keras.optimizers.Adam(learning_rate=1e-5),
               loss=tf.keras.losses.SparseCategoricalCrossentropy(from_logits=True),
               metrics=['accuracy'])

history1 = model1.fit(train_images_noise, train_labels, batch_size=100, epochs=5,
                     validation_data=(test_images, test_labels))
```



# Program of KOL

```

kernel_shape = (self.kernel_size[0], self.kernel_size[1], input_shape[-1], self.filters)

def Q(t):
    return 2*t**2-1

def F_K(theta_1, theta_2, x, y):
    return math.sin(theta_2)*(math.cos(theta_1)*x+math.sin(theta_1)*y)+math.cos(theta_2)*Q(math.cos(theta_1)*x+math.sin(theta_1)*y)

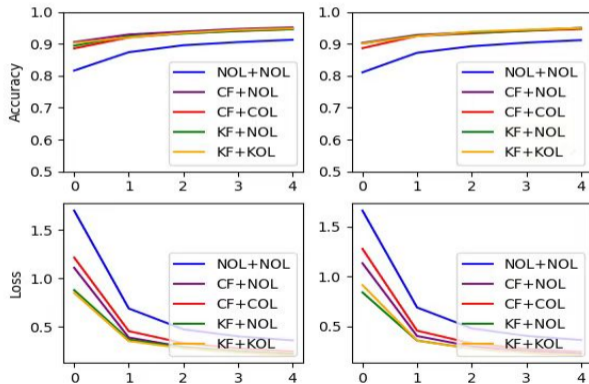
def D(a_1,a_2,b_1,b_2):
    return np.power(dblquad(lambda y,x:(F_K(a_1, a_2, x, y)-F_K(b_1, b_2, x, y))**2,#函数
        -1,#x下界0
        1,#x上界pi
        lambda x:-1,#y下界x^2
        lambda x:1, 1/2)[0],#y上界2*x

temp_3 = tf.zeros(shape=kernel_shape, dtype=tf.float32).numpy()
for i in range(input_shape[-1]):
    for j in range(self.filters):
        if D(i%8 * math.pi/int(math.sqrt(input_shape[-1])), i//int(math.sqrt(input_shape[-1])) * 2* math.pi/int(math.sqrt(input_shape[-1]))):
            temp_3[:, :, i, j] = tf.ones(shape=(self.kernel_size[0], self.kernel_size[1]), dtype=tf.float32).numpy()
self.mask = tf.constant(temp_3)
self.kernel = self.add_weight(name='kernel', shape=kernel_shape, initializer='glorot_uniform', trainable=True)
self.bias = self.add_weight(name='bias', shape=(self.filters,), initializer='zeros', trainable=True)

```



# A Result of TCNN on MNIST



Thanks for your listening!